

goo.gl/VdqqXC

LoRaWAN IoT with Arduino Uno, Dragino v1.3 & TheThingsNetwork

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for /ch/open, September 2017 & make-munich.de, May 2017 & /ch/open, September 2016

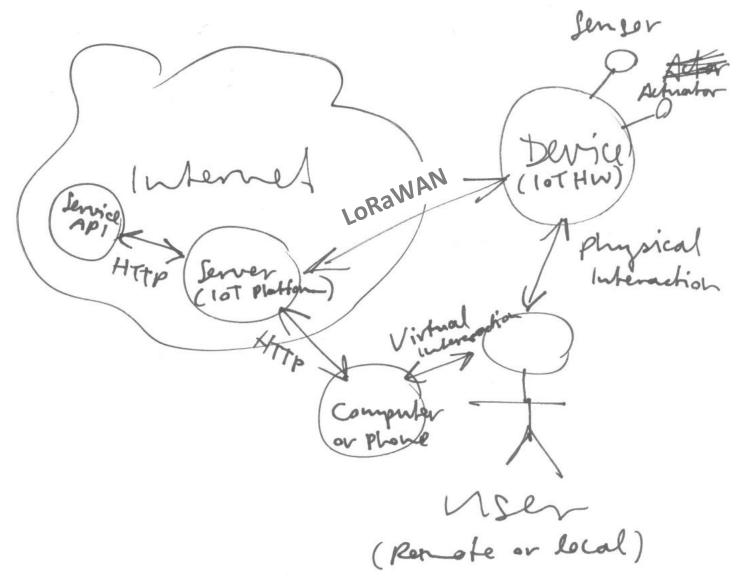
Internet of Things (IoT)

Computers with **sensors** and **actuators**, **connected** through Internet protocols.

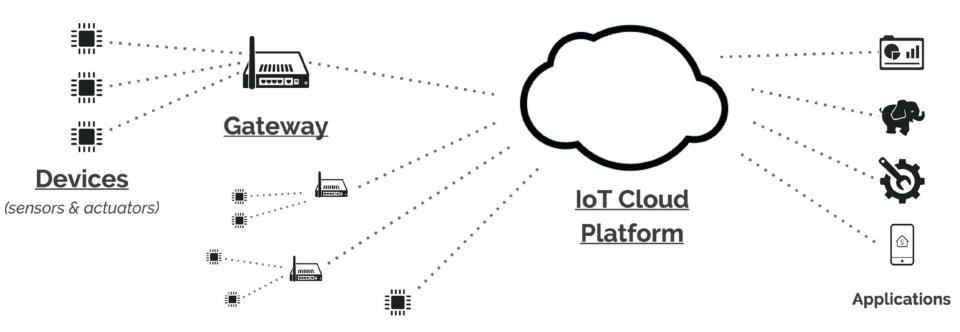
Instead of just accessing and editing virtual resources, we can now measure and manipulate **physical properties**.

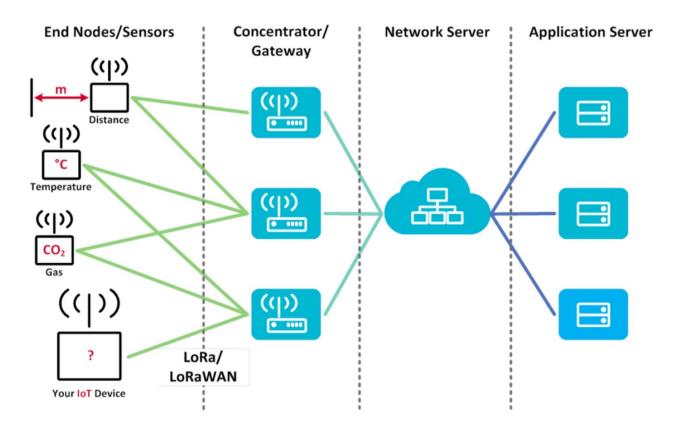
For developers: IoT = physical objects with an API.

IoT reference model



IoT reference model





- End Nodes/Sensors measure values and transmit the data
- Concentrator/Gateway receive the radio packets and trasmit them to the network server over LAN, Cell, ...
- Network Server forwards and/or collects data from the end nodes/sensors
- Application Server makes something useful out of the data. Usually your server or application, that simplyfies your customers life

LoRa & LoRaWAN

Wireless communication network focused on low power, long range and low cost.

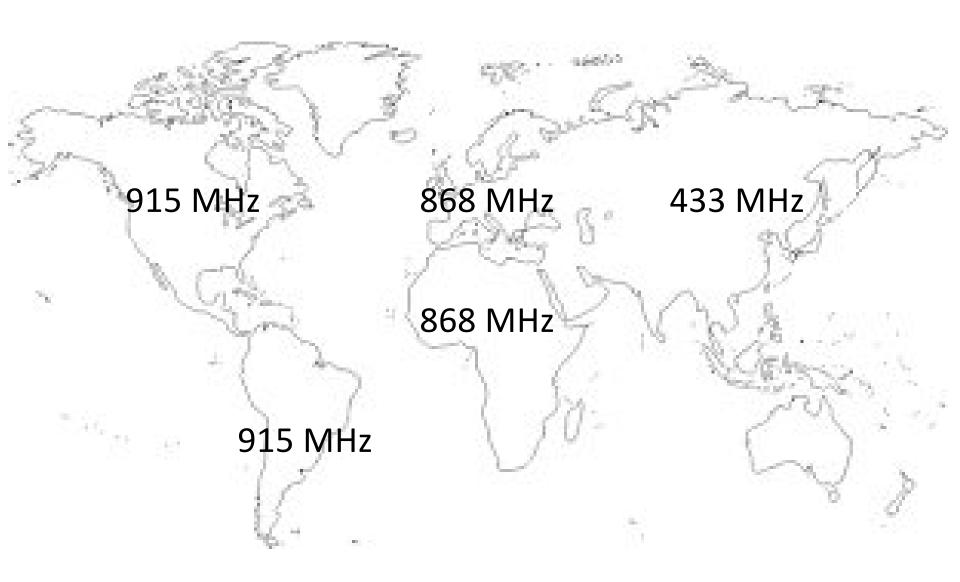
Power: ~14mA (RX), ~28mA (TX)

Cost: ~\$10 (modem), ~\$300 (gateway)

Range: 5km (urban) to +40km (rural)

https://www.lora-alliance.org/What-Is-LoRa

LoRa Spektrum



The Things Network

A **global community**, building **open source** software and hardware to operate a **crowd-sourced** LoRa network.

https://www.thethingsnetwork.org/



Topics of this workshop

- 1) Getting started with Arduino
- 2) Using sensors and actuators with Arduino
- 3) Connecting to LoRaWAN w/ TheThingsNetwork
- 4) Sending sensor data via LoRaWAN with Imic
- 5) Forwarding sensor data to ThingSpeak, IFTTT
- 6) Sending downlink messages to the Arduino
- 7) Deploying a node with a weatherproof case
- 8) Deploying a TTN gateway walk through

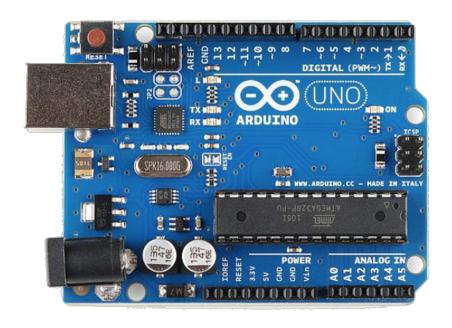
Questions? Just ask / Use Google / Help each other

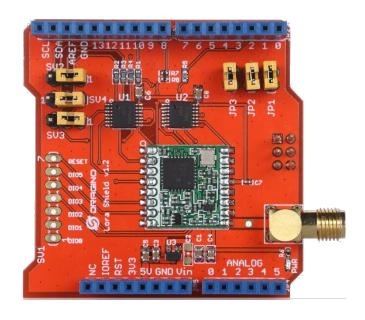
1) Getting Started

How to set up the Arduino – the basics of embedded programming, step by step.

Hardware

This tutorial is based on the **Arduino** Uno board and the Dragino v1.3 **LoRa shield**





Note: For the first part we just need the Arduino Uno

Getting started

The **IDE** (Integrated **D**evelopment **E**nvironment) allows you to **program** your board, i.e. "make it do something new"

You **edit** a program on your computer, then **upload** it to your board where it's stored in the program memory (flash) and **executed** in RAM

Note: Once it has been programmed, your board can run on its own, without another computer

Download and install Arduino.cc

To install the **Arduino IDE** and connect your Arduino board to your computer via USB, see

http://arduino.cc/en/Guide/MacOSX or

http://arduino.cc/en/Guide/Windows or

http://arduino.cc/playground/Learning/Linux

Or install https://codebender.cc/static/plugin and use the https://codebender.cc/ online IDE

Note: Codebender is great, but has some limitations

Examples included with Arduino

Go to *File > Examples > Basics* to open the *Blink* example, scroll down to see the actual code



Note: All Arduino libraries come with examples, too

Upload code to your Arduino

Select *Tools > Board > Arduino/Genuino Uno* and set the right USB port in the *Port* menu, then click *Upload*

```
Woid setup() {
    pinMode(13, OUTPUT);
}

void loop() {
    digitalWrite(13, HIGH);
    delay(1000);
    digitalWrite(13, LOW);
    delay(1000);
}
```

Note: clicking Upload also compiles the source code

Hello, World! (serial output)

```
void setup () { // run once
 Serial.begin(9600); // set baud rate
void loop () { // run again and again
 Serial.println("Hello, World!"); // print output
```

Note: type this program code into your IDE and upload it to the device, then check the next slide

Serial output with Arduino

Click the *Serial Monitor* icon to see serial output, and make sure the baud rate (e.g. *9600*) matches your code



Note: Serial output is great to debug your program

Se lit

The **source code** of slides with a blue ribbon is available online, just click the link to display it.

Or download the ZIP from https://bitbucket.org/ tamberg/iotworkshop/get/tip.zip

Or browse code online at https://bitbucket.org/ tamberg/iotworkshop/src/tip

Note: use the *Raw* button to see files as plain text

2) Using sensors and actuators

How to measure and manipulate physical properties with sensors and actuators – the basics of electronics, interactive systems and physical computing, in a few easy examples.

Inputs and outputs

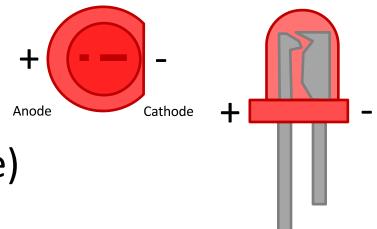
IoT hardware has an interface to the real world.

GPIO (General Purpose Input/Output) pins.

Measure: **read** sensor value from **input** pin Manipulate: **write** actuator value to **output** pin.

Inputs and outputs can be digital or analog.

The LED

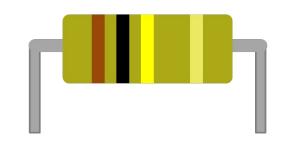


The **LED** (**L**ight **E**mitting **D**iode) is a simple digital **actuator**

LEDs have a **short leg** (-) and a **long leg** (+) and it matters how they are oriented in a circuit

To prevent damage, LEDs are used together with a $1K\Omega$ resistor (or anything from 300Ω to $2K\Omega$)

The resistor



Resistors are the workhorse of electronics

Resistance is **measured in \Omega** (Ohm)

A resistors orientation does not matter

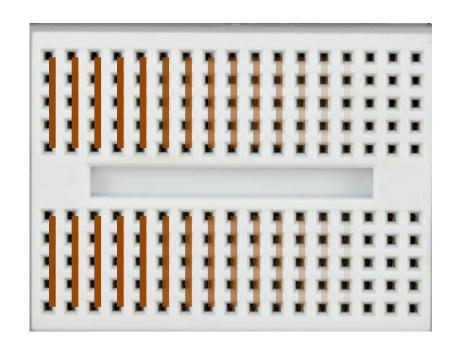
A resistors Ω value is **color-coded** right on it

Note: color codes are great, but it's easier to use a multi-meter if you've got one, and just measure Ω

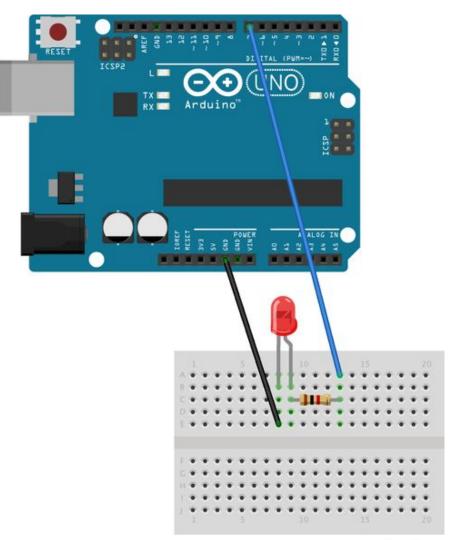
The breadboard

A breadboard lets you wire electronic components without any soldering

Its holes are connected "under the hood" as shown here



Wiring a LED with Arduino



Note: the additional $1K \Omega$ resistor should be used to prevent damage to the pins / LED if it's reversed

The long leg of the LED is connected to pin D7, the short leg to ground (GND)

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Outour in

Blinking a LED (digital output)

```
int ledPin = 7;
void setup () {
  pinMode(ledPin, OUTPUT);
void loop () {
  digitalWrite(ledPin, HIGH);
  delay(500); // wait 500ms
  digitalWrite(ledPin, LOW);
  delay(500);
```

Get code here ↗

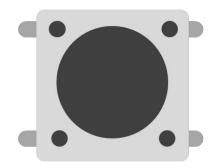
Blinking an LED is the *Hello World* of embedded software

Set *ledPin* as wired in your LED circuit

```
HIGH = digital 1 (5V)
means LED is on,
LOW = digital 0 (0V)
means LED is off
```

The switch

A switch is a simple, digital sensor

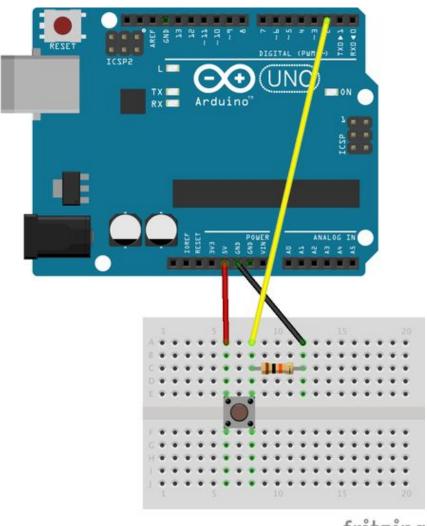


Switches come in different forms, but all of them in some way **open** or **close** a gap in a wire

The **pushbutton** switch has four legs for easier mounting, but only two of them are needed

Note: you can also easily build your own switches, for inspiration see e.g. http://vimeo.com/2286673

Wiring a switch with Arduino



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Note: the resistor in this setup is called pull-down 'cause it pulls the pin voltage down to GND (0V) if the switch is open

Pushbutton switch

10K Ω resistor

5V

GND

2 (max input 5V!)

Induction 1

Reading a switch (digital input)

```
int sensorPin = 2; // e.g. button switch
void setup () {
  Serial.begin(9600); // set baud rate
  pinMode(sensorPin, INPUT);
void loop () {
  int sensorValue = digitalRead(sensorPin);
  Serial.println(sensorValue); // print 0 or 1
```

Open the IDE serial monitor or terminal to see log output

Switcheo !ino

Switching a LED

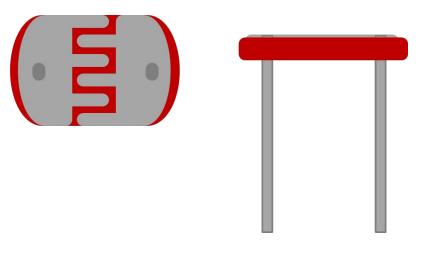
```
int switchPin = 2;
int ledPin = 7; // or 13
void setup () {
  pinMode(switchPin, INPUT);
  pinMode(ledPin, OUTPUT);
void loop () {
  int switchValue = digitalRead(switchPin);
  if (switchValue == 0) {
    digitalWrite(ledPin, LOW);
  } else { // switchValue == 1
    digitalWrite(ledPin, HIGH);
```

Note: figure out the wiring or just use the built-in LED, i.e. pin 13 on Arduino

The code inside an *if* statement is only executed if the condition is true, *else* is executed otherwise

The LDR

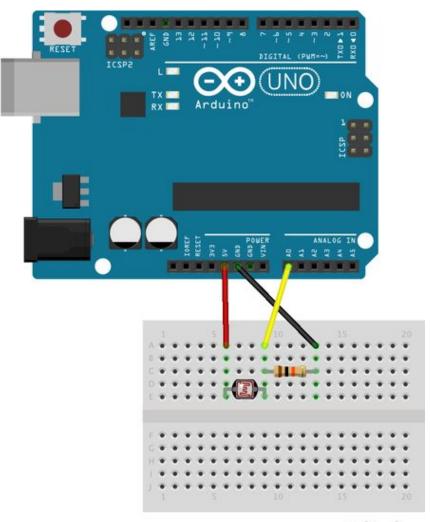
A photoresistor or **LDR** (light dependent resistor) is a resistor whose resistance depends on light intensity



An LDR can be used as a simple, analog sensor

The orientation of an LDR does not matter

Wiring an LDR with Arduino



Note: this setup is a voltage-divider, as the 5V total voltage is divided between LDR and resistor to keep 0V < AO < 2.5V

Photoresistor (LDR)

10K Ω resistor

5V

GND

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Inour ino

Reading an LDR (analog input)

```
int sensorPin = A0; // LDR or other analog sensor

void setup () {
    Serial.begin(9600); // set baud rate
}

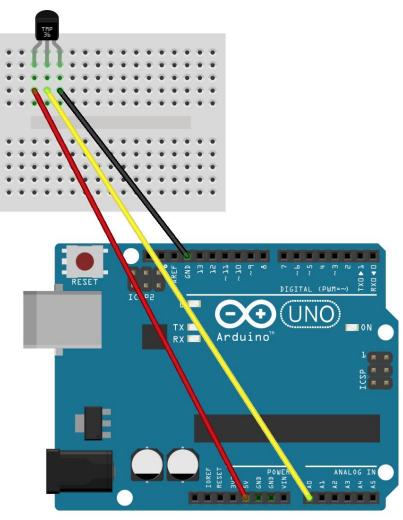
Open the IDE serial monitor or terminal to see log output

void loop () {
    int sensorValue = analogRead(sensorPin);
```

Note: use e.g. Excel to visualize values over time

Serial.println(sensorValue); // print value

Wiring a TMP36 with Arduino



fritzing

Note: TMP36 is a cheap temperature sensor, so it is not very accurate. But a qualitative value can be read from it

Sensor (TMP36)

5V

GND

A₀

```
Reading a TMP36 (analog input)
```

```
int sensorPin = A0; // TMP36
void setup () {
  Serial.begin(9600); // set baud rate
void loop () {
  int sensorValue = analogRead(sensorPin);
  float voltage = (sensorValue * 5.0) / 1024.0;
  float tempCelsius = (voltage - 0.5) * 100;
  Serial.println(tempCelsius);
```

Open the IDE serial monitor or terminal to see log output

The Servo

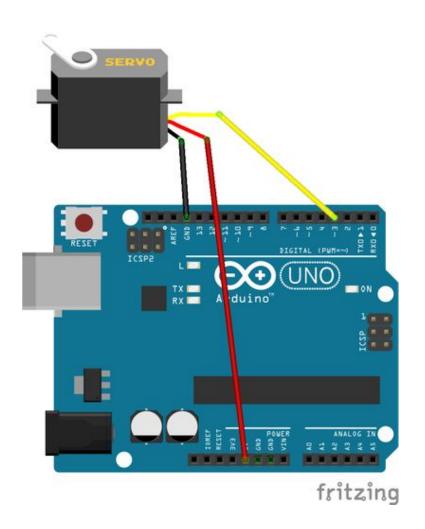
A **servo** motor takes an input between 0 and 180 which is translated into a motor position in degrees



A servo is an analog actuator

To create an analog output for the servo, the device uses pulse width modulation (**PWM**)

Wiring a Servo with Arduino



Note: PWM pins on Arduino are those with a ~ symbol

5V GND D3 (PWM)

Controlling a Servo (PWM output)

```
#include <Servo.h> // remove this line on the Photon
Servo servo; // create a new Servo object
int servoPin = 3; // a PWM pin
void setup () {
  servo.attach(servoPin);
void loop () {
  for (int pos = 0; pos \leq 180; pos \neq 10) {
    servo.write(pos);
    delay(100);
```

Note: *Servo* objects let you use Servos without PWM skills

The *for* loop repeats from pos 0 until pos is 180, in steps of 10



Controlling a Servo with an LDR

```
#include <Servo.h> // remove this line on the Photon
Servo servo; // create a new Servo
int servoPin = 3; // a PWM pin
int sensorPin = A0; // LDR
void setup () {
  servo.attach(servoPin);
void loop () {
  int val = analogRead(sensorPin);
  int pos = map(val, 0, 255, 0, 180);
  servo.write(pos);
```

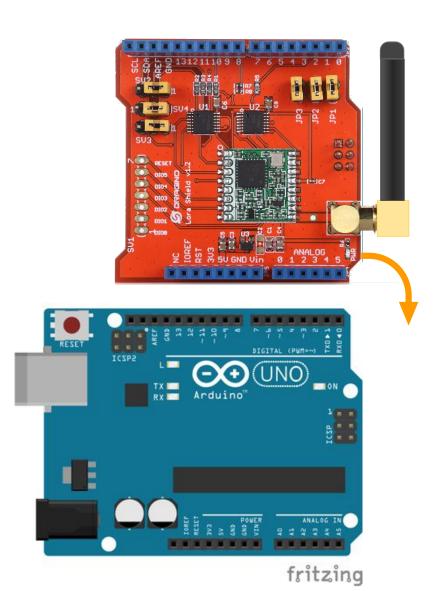
Note: combine the wiring diagrams of both, Servo & LDR

The *map* function is useful to map one range onto another

3) Connecting to LoRaWAN

How to get network and application keys and connect your Arduino to the LoRa wide area network provided by TheThingsNetwork.

Adding the Dragino LoRa shield

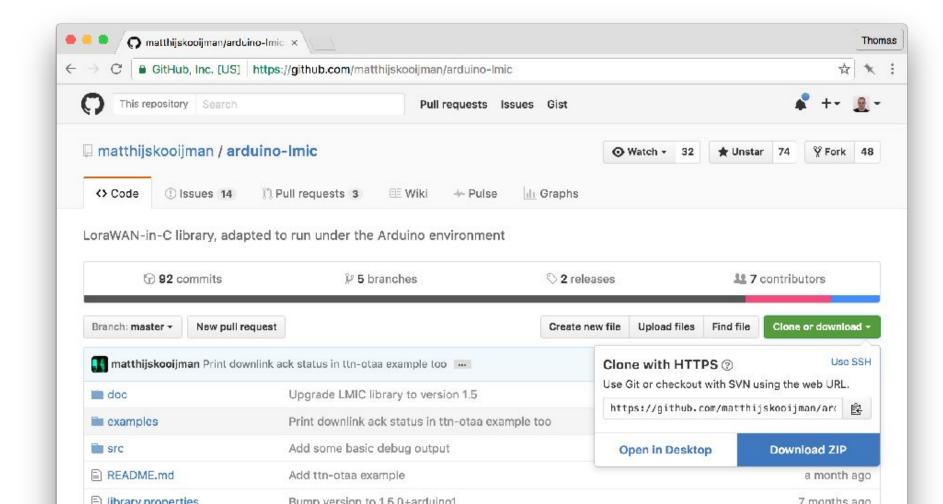


Note: the LoRa shield stacks onto the Arduino - just make sure the pins line up properly

Pin 2 and pins 6 - 13 are used by the Lora shield according to http://playground. arduino.cc/Main/ShieldPinUsage

Installing the Imic Arduino library

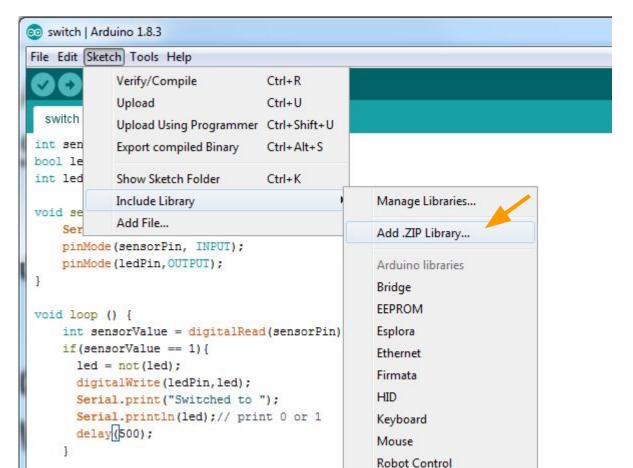
Download ZIP from github:



Installing the Imic Arduino library

Add library to IDE:

Sketch > Include Library > Add ZIP Library



Installing the Imic Arduino library

OR

Mac:

extract ZIP to ~/Documents/Arduino/libraries/Imic

Windows:

extract ZIP to

C:\Users\USER_NAME\Documents\Arduino\Libraries\Imic

Linux:

cd ~/Arduino/Libraries/

git clone https://github.com/matthijskooijman/arduino-lmic.git

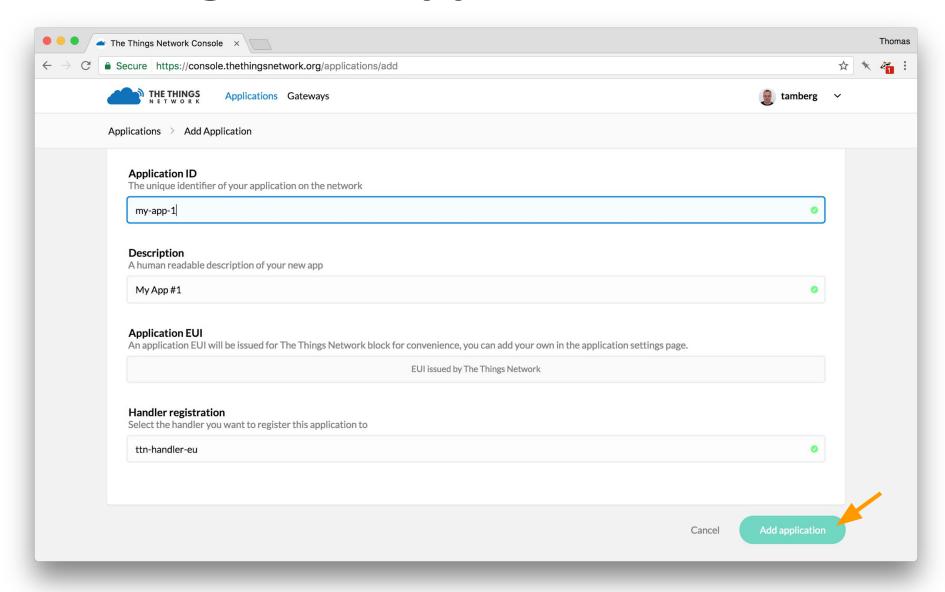
Adding a TTN application

https://console.thethingsnetwork.org/applications
(register to get an account, if needed)

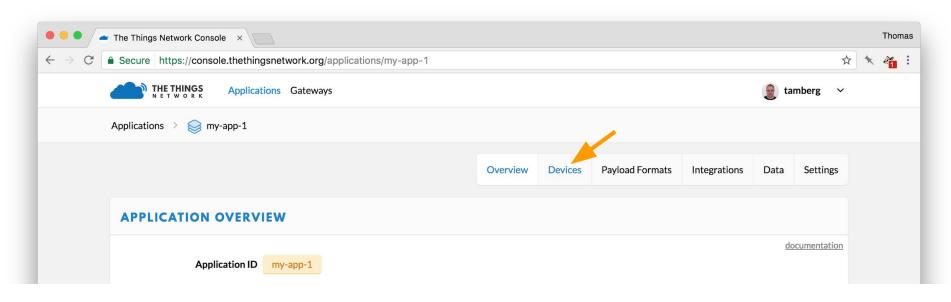


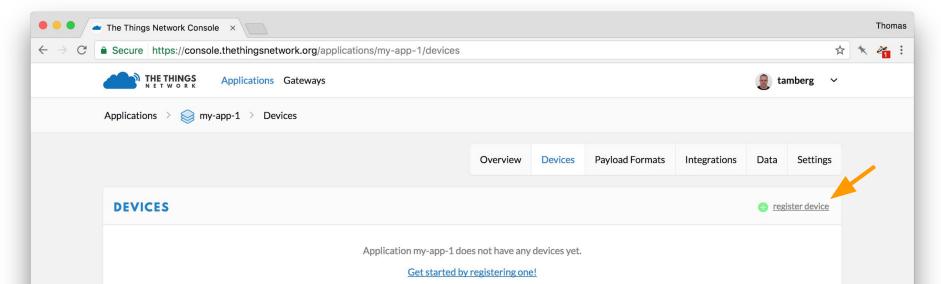


Adding a TTN application

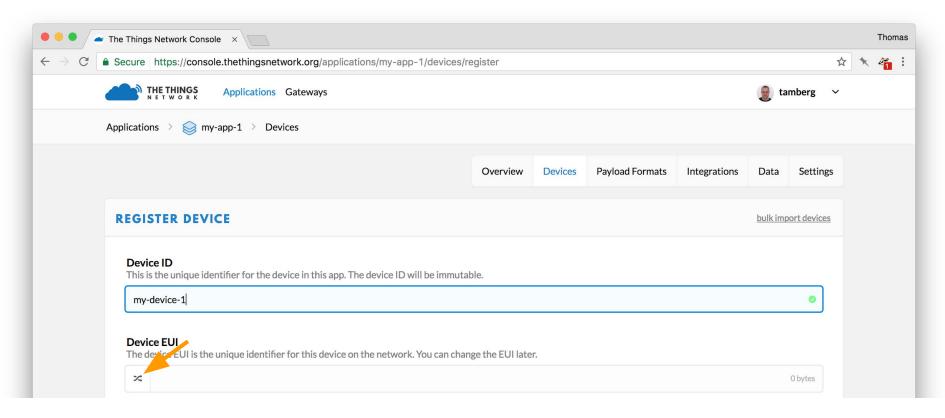


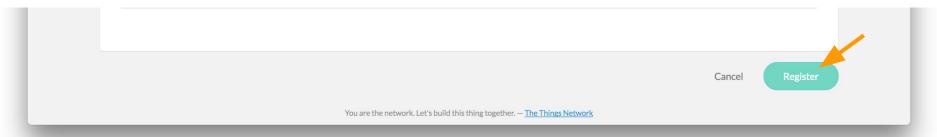
Registering a device



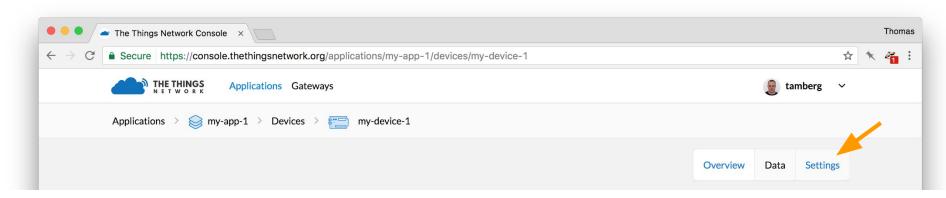


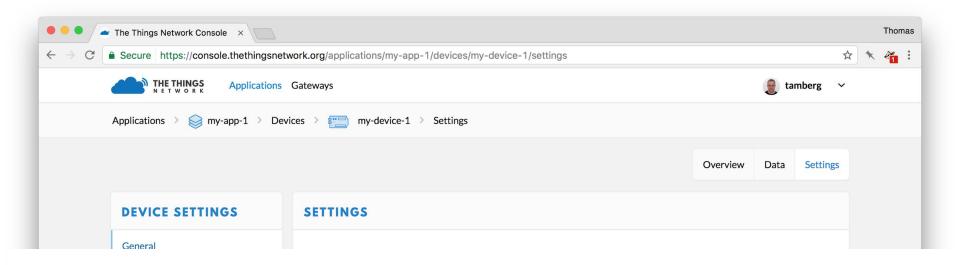
Registering a device





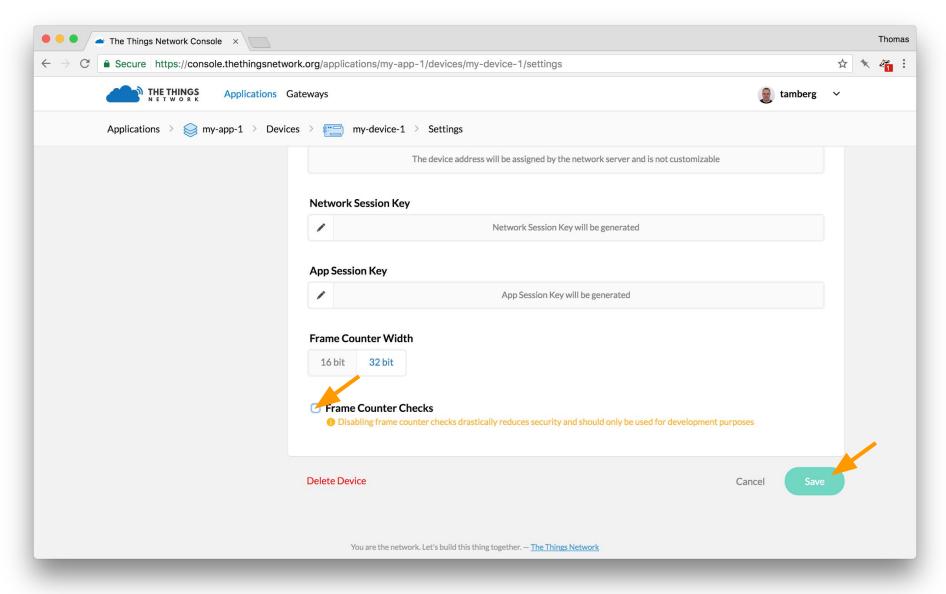
Registering a device with ABP



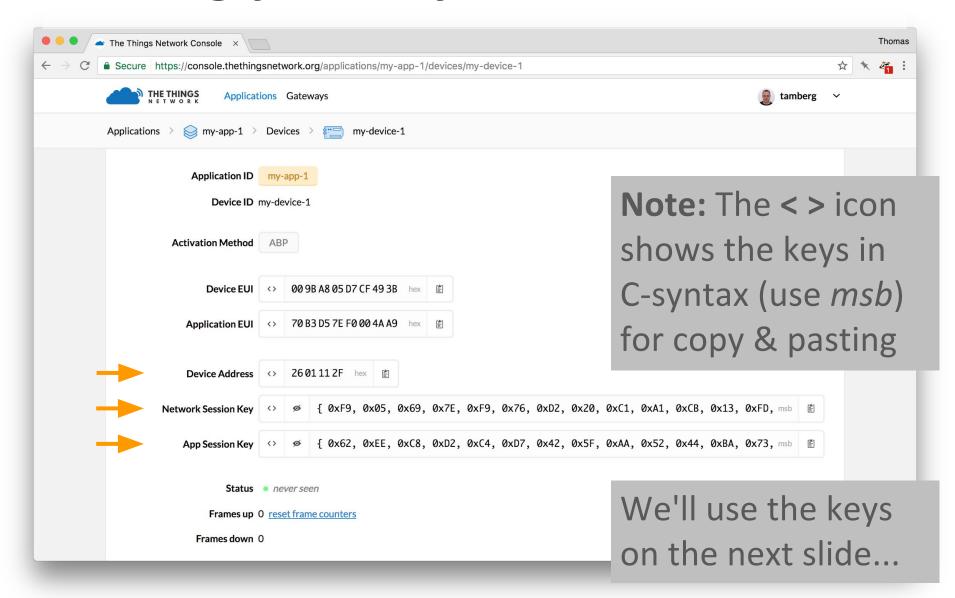




Registering a device with ABP



Getting your keys



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Setting your keys in the code

```
#include < lmic.h > ...
static const u4 t DEVADDR = 0x01234567;
static const u1_t NWKSKEY[16] = {
  // e.g. for 00 11 22 33 44 55 66 77 88 99 AA BB CC DD EE FF
  0x00, 0x11, 0x22, 0x33, 0x44, 0x55, 0x66, 0x77,
                                                   The 0x.. is
  0x88, 0x99, 0xAA, 0xBB, 0xCC, 0xDD, 0xEE, 0xFF
                                                   important
};
static const u1_t APPSKEY[16] = {
  0x??, 0x??, 0x??, 0x??, 0x??, 0x??, 0x??, 0x??,
                                                   Same here
  0x??, 0x??, 0x??, 0x??, 0x??, 0x??, 0x??, 0x??
   We will test this in the next chapter by sending text
```

4) Sending data

How to encode and transfer data packets to the TheThingsNetwork back-end server.

We'll be using the keys from the previous part for all examples.

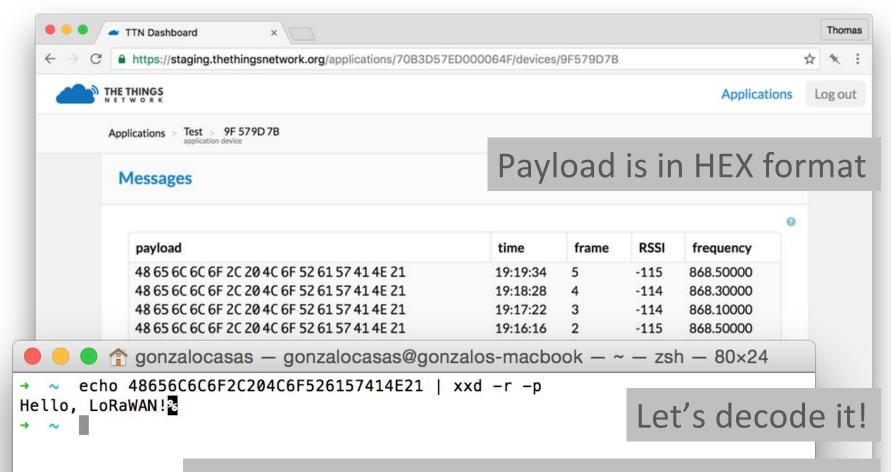
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Sending text with LoRaWAN

```
#include < lmic.h > ...
                                 Details do not matter here.
void do_send(osjob t* j) {
  static uint8_t message[] = "Hello, LoRaWAN!"; // ASCII only
  if ((LMIC.opmode & OP TXRXPEND) == 0) { // ok to send
    LMIC_setTxData2(1, message, sizeof(message) - 1, 0);
       Queue message to be sent after next TXCOMPLETE
void onEvent (ev t ev) { ...
  case EV_TXCOMPLETE: os_setTimedCallback(..., do_send); ...
```

Note: The **Imic** library is currently the most robust way to use the HopeRF chip, which is on the Dragino shield. A easier to use library might come. You're an early adopter.

Viewing data in the dashboard

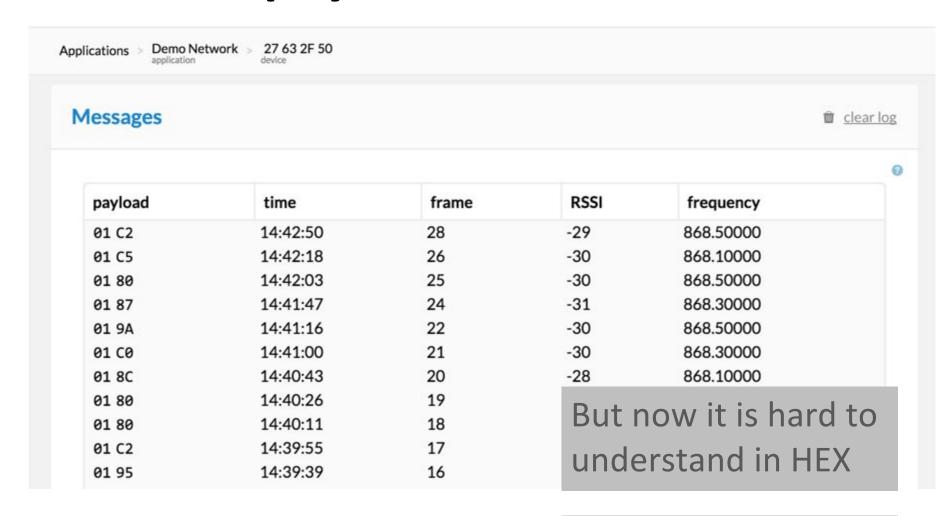


On Windows, use an online decoder, e.g.: http://www.dolcevie.com/js/converter.html

Sending numbers with LoRaWAN

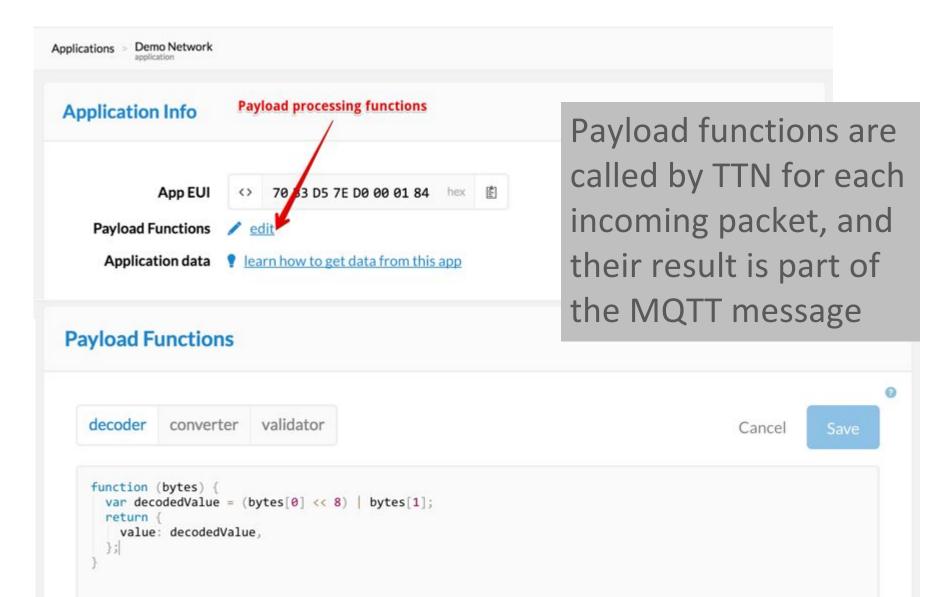
```
#include <lmic.h> ...
void do_send(osjob t* j) {
                                       An integer is 2 bytes
  int value = analogRead(A0);
  static uint8_t message[2];
                                     Put the high and low
  message[0] = highByte(value);
                                     byte into the message
  message[1] = lowByte(value);
  if ((LMIC.opmode & OP_TXRXPEND) == 0) { // ok to send
    LMIC_setTxData2(1, message, sizeof(message), 0);
void onEvent (ev_t ev) { ...
  case EV_TXCOMPLETE: os_setTimedCallback(..., do_send); ...
```

Numeric payload in the dashboard



Let's make it easier!

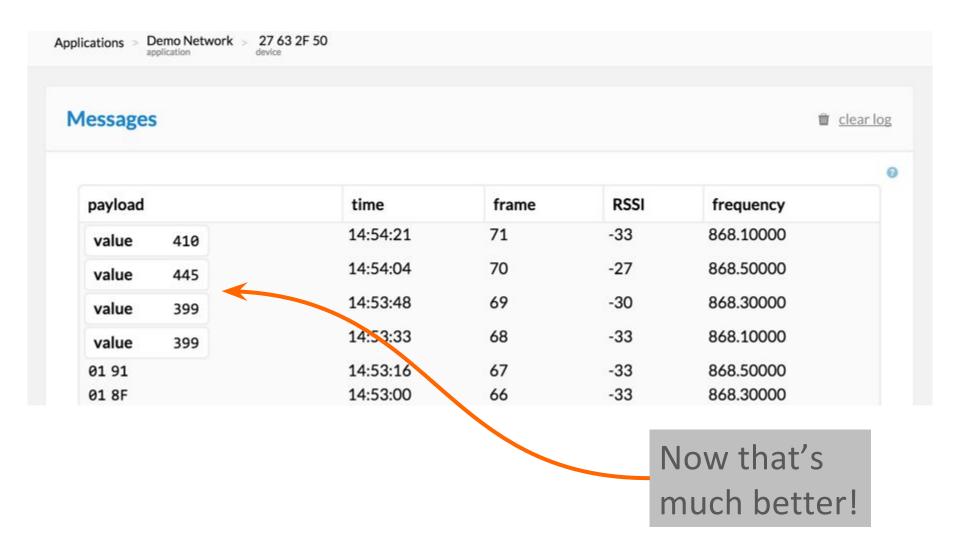
Payload functions to the rescue!



Writing a decoder function

```
function (bytes) {
 var decodedValue = (bytes[0] << 8) | bytes[1];</pre>
 return {
                                       Payload functions are
  value: decodedValue,
                                       written in Javascript
                                       Take the first two
                                       bytes, combine them
           Payload Functions
                                       and return an object
                                       Note: bytes is the
             decoder
                            validator
                    converter
                                                                      Cancel
                                       name of a variable
             function (bytes) {
               var decodedValue = (bytes[0] << 8) | t</pre>
                                       here, not a data type
                value: decodedValue.
```

Decoded payload in the dashboard



Types of payload functions

Decoders transform bytes to objects, e.g. an analogRead PIN into a Celsius temperature.

Converters transform the output of decoders even further, e.g. from Celsius to Fahrenheit.

Validators make sure the data is correct, i.e. check the values are not outliers.

5) Forwarding sensor data

Messages sent via LoRaWAN to the network server of TheThingsNetwork become available through the MQTT messaging protocol.

We use a simple Node.js MQTT client to fetch our messages and forward them to ThingSpeak, a storage for sensor data or IFTTT, a rule based platform for mash-ups with 3rd-party services.

Installing Node.js on Mac or PC

Install Node.js from https://nodejs.org/en/

Create a text file named **hello.js** containing console.log("hello");

Open a **terminal** at the same location and type \$ node hello.js

```
NodeJS — bash — 80×24

bash

mac:NodeJS tamberg$ node hello.js
hello
mac:NodeJS tamberg$ ■
```

Installing the ttn Node.js library

Create a new folder for your Node.js project

Open a terminal at the same location and type

- \$ npm update
- \$ npm install ttn --save



Getting your data with Node.js

In your Node.js project directory, download the *ttn-mqtt-logger* code (use the link or next page)

To install the ttn library, type

\$ npm install ttn --save

To run the Node.js code, type

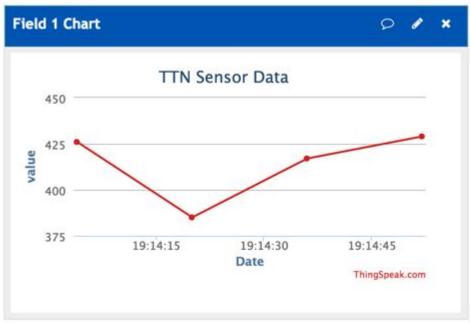
\$ node ttn-mqtt-logger.js

Incoming LoRaWAN packets should now be logged

Visualising data with ThingSpeak

The ThingSpeak service lets you store, **monitor** and share **sensor data** in open formats. Sign up at https://thingspeak.com/ to create a channel and get API keys.

Let's add it to our Node.js client.



Forwarding data to ThingSpeak

```
var http = require('http');
client.on('uplink', function (msg) {
 http.get('http://api.thingspeak.com/update?' +
    'api_key=WRITE_API_KEY' +
    '&field1=' + msg.fields.value);
});
```

Open a terminal at your Node.js project location, type \$ node ttn-thingspeak-forwarder.js

Send some numbers with *DraginoTtnAbpTxInt.ino* then check https://thingspeak.com/channels/CHANNEL_ID

Mash-up cloud services with IFTTT

If This Then That (IFTTT) is a mash-up platform

An IFTTT Recipe connects two Web services (or a service and a device) using their Web **API**s

The IFTTT Maker Channel uses Webhooks (outgoing HTTP requests) to call your device, and you can use Web requests to trigger IFTTT

Forwarding data to IFTTT

Download the *ttn-ifttt-forwarder.js*, and set the keys.

```
var appEUI = 'TTN_APP_EUI';
var accessKey = 'TTN_ACCESS_KEY=';
var makerChannelKey = 'IFTTT_MAKER_CHANNEL_KEY';
...
Comments =>
how to get key
```

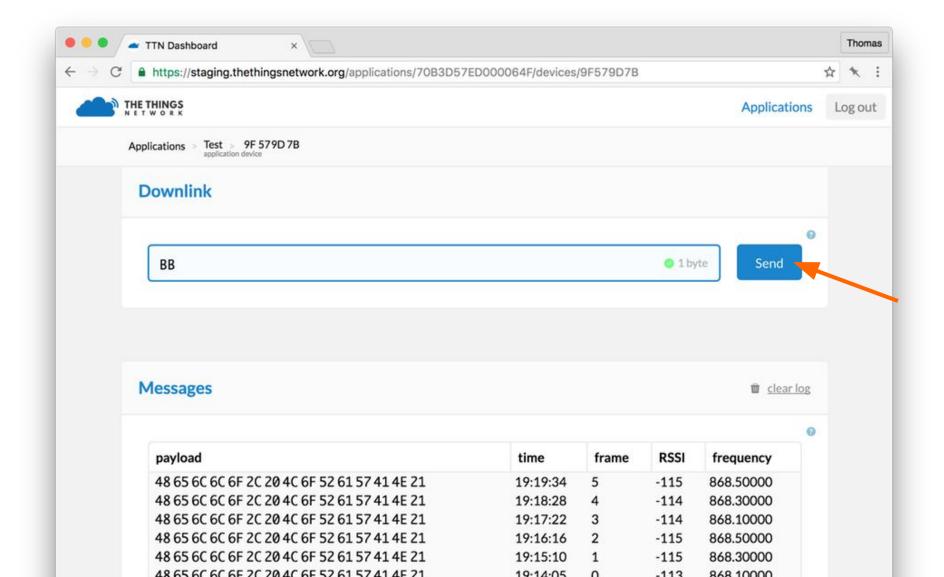
Open a terminal at your Node.js project location, type \$ node ttn-ifttt-forwarder.js

Create a recipe on IFTTT using the Maker channel, e.g. https://ifttt.com/recipes/335901-lorawan-log

6) Sending downlink messages

How to send data from the TheThingsNetwork backend to the LoRaWAN node

Sending data to your Arduino



Receiving data on the Arduino

```
#include < lmic.h > ...
void onEvent (ev t ev) {
 if (ev == EV TXCOMPLETE) {
    if (LMIC.dataLen) {
       uint8_t data[LMIC.dataLen];
       memcpy(&data, &(LMIC.frame + LMIC.dataBeg)[0],
          LMIC.dataLen);
       for (int i = 0; i < LMIC.dataLen; i++) {
          Serial.println(data[i]);
   // Schedule next transmission
   os setTimedCallback(&sendjob, os getTime()+sec2osticks(TX INTERVAL), do send);
```

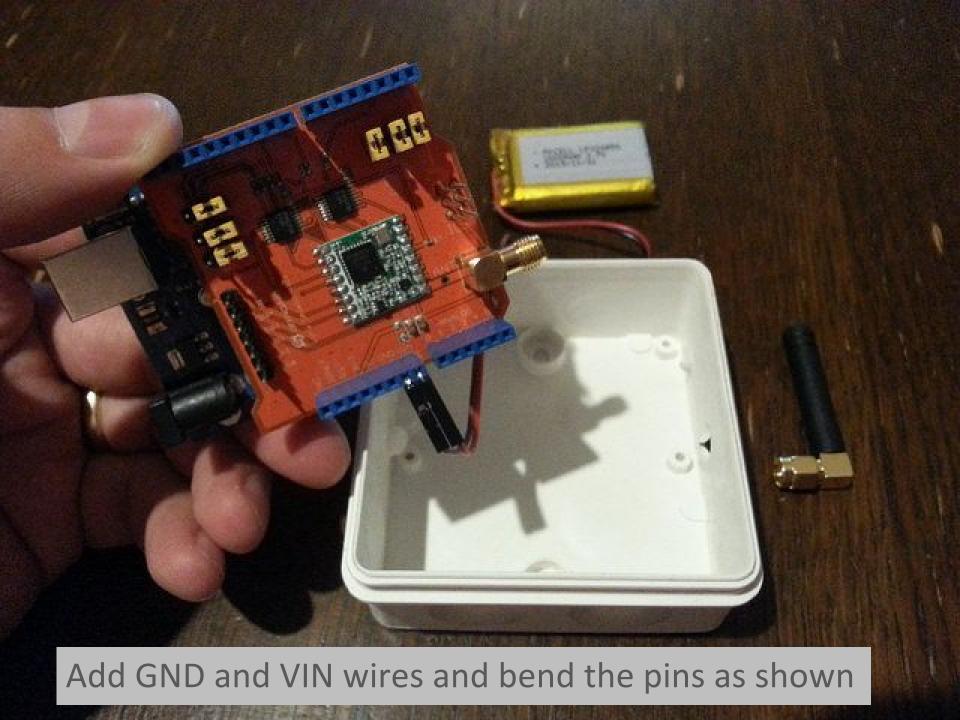
Ontrolling Arguit

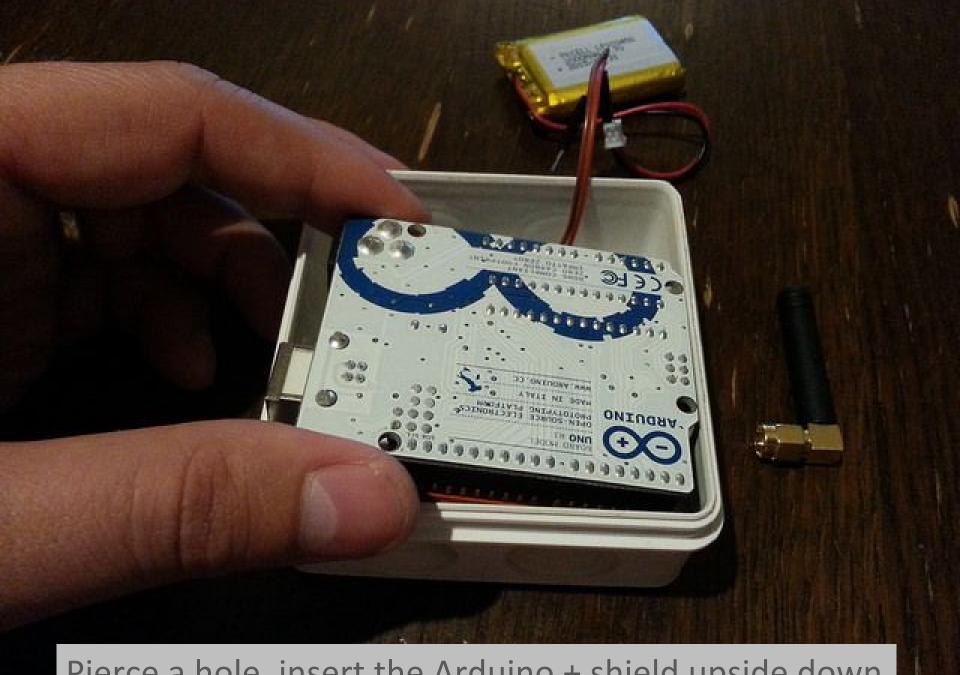
Controlling an LED remotely

```
#include < lmic.h > ...
                                                   Add a LED on D5
void setup () { ... pinMode(5, OUTPUT); ... }
void onEvent (ev t ev) {
 if (ev == EV_TXCOMPLETE) {
   if (LMIC.dataLen) {
                                                   Parse downlink
      uint8_t downlink[LMIC.dataLen];
      memcpy(&downlink,
        &(LMIC.frame+LMIC.dataBeg)[0],LMIC.dataLen);
     digitalWrite(5, downlink[0] == 42);
                                                   Use its value to
                                                   turn LED on/off
   // Schedule next transmission
   os_setTimedCallback(&sendjob, os_getTime()+sec2osticks(TX_INTERVAL), do_send);
```

7) Deploying a node

How to add a watertight case around the LoRa node and power it either by battery or a used USB cable cut and prepared for our needs.

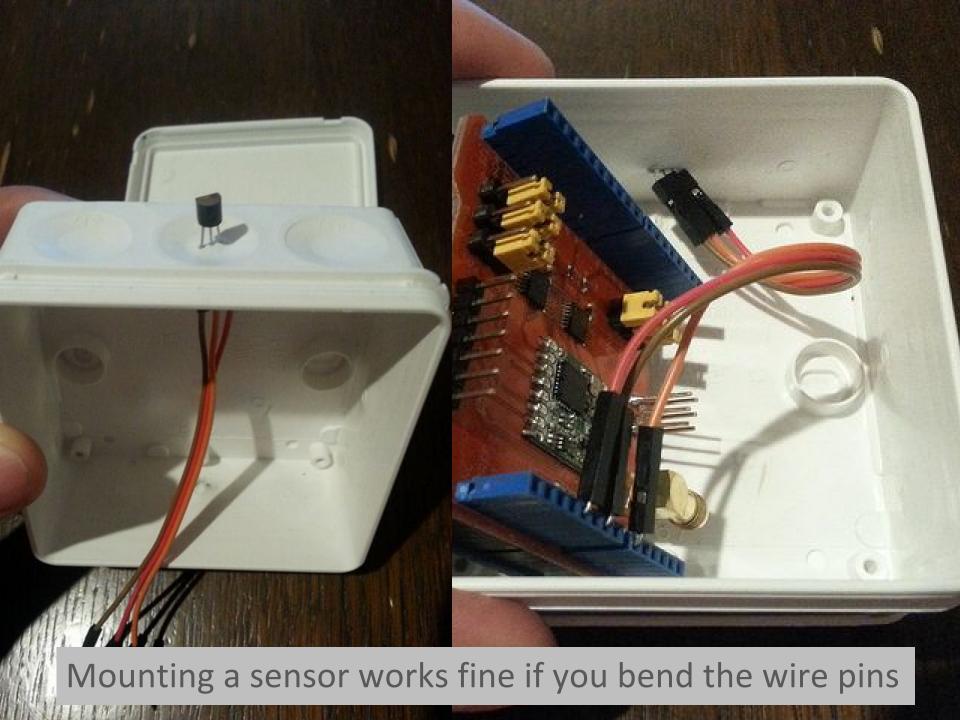




Pierce a hole, insert the Arduino + shield upside down

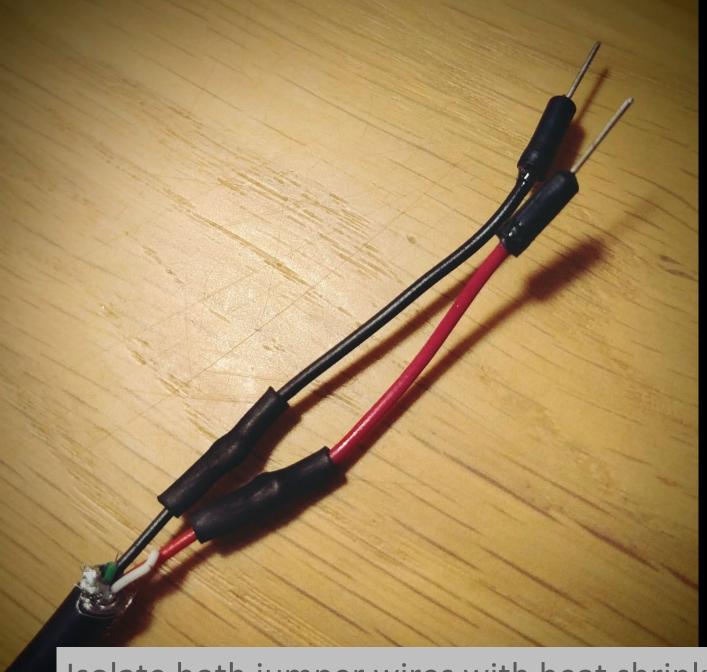


Connect antenna, then connect (battery or USB) power





Cut an old USB cable, solder jumper wire to red, black



Isolate both jumper wires with heat shrink tubing

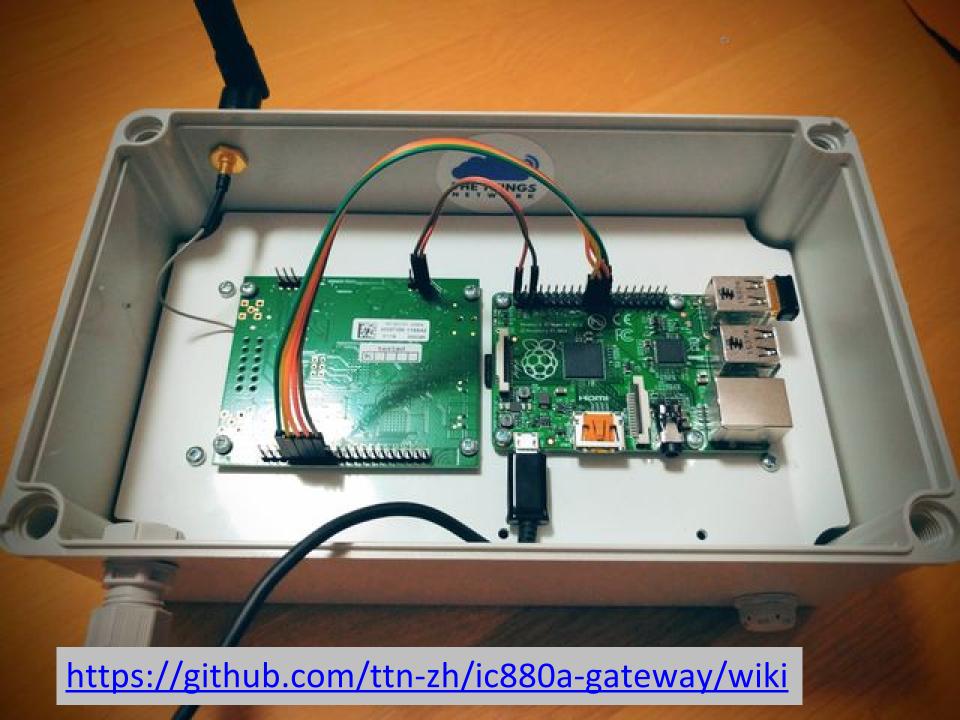


Thread the USB cable through, fix it with a zip tie

8) Deploying a TTN gateway

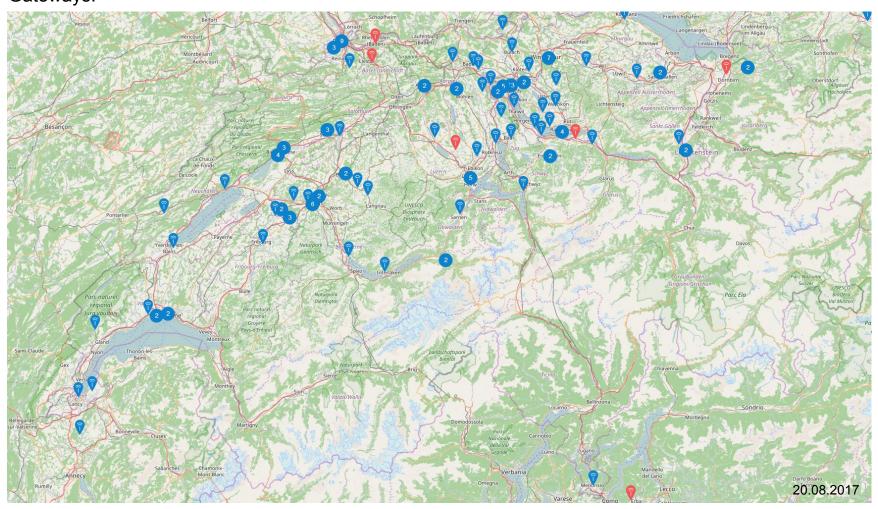
Do you want to extend the TTN coverage in your area? Build a gateway, it's easy and fun. And also pretty cheap (~300 CHF) compared to commercial alternatives (between 500 CHF and 1600 CHF).

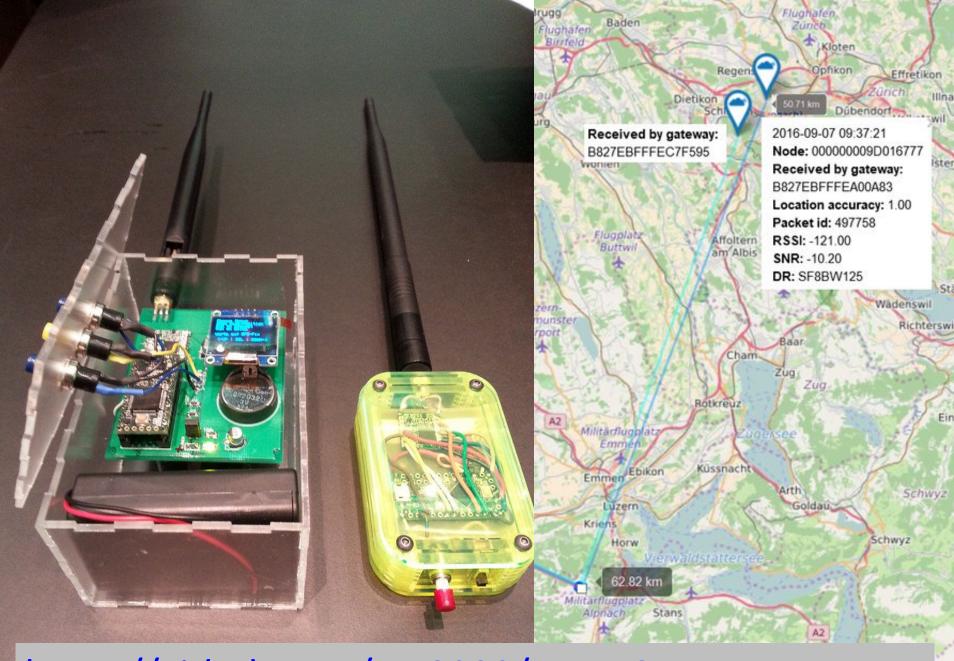
Once the gateway is up, you can measure the network coverage with simple means. Add a GPS to your node, or use your phone's GPS to record the time and place a packet was sent.



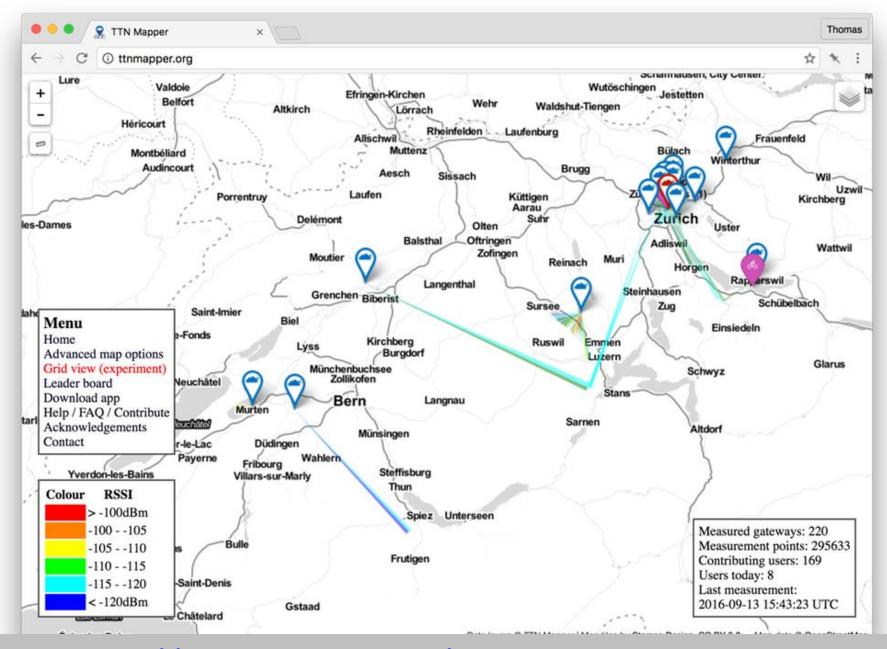
The Things Network CH

Gateways:





https://github.com/urs8000/LoRa-Gateway-Locator



Try http://ttnmapper.org/ and the ttnmapper app

Appendix A - Limitations

Why not just send ASCII?

Duty Cycle limitations:

Only 1% air time allowed on these frequencies.

TTN's Fair Usage policy:

30 seconds of airtime/day for uplink 10 downlink/day

smaller more payload messages/day

How much data can be sent?

LoRaWAN protocol adds 13 bytes (at least)

Spreading Factor (SF) affects airtime required SF7 = Most efficient, SF12 = Least efficient

Pack payload in binary as efficiently as possible

Use **built-in features** to **reduce data** (ports for data types, built-in counter, etc).

How much data can be sent?

	Payload sample	Payload/Total size	Msg/day
Simple payload	{ "Count": 1234, "Temperature": 20.635 }	40/53	292
Remove counter	{"t":20.63}	11/24	486
No JSON	20.63	5/18	582
16-bits integer	0x080F	2/15	648

Here's an <u>air time calculator</u> spreadsheet

Why is downlink so limited?

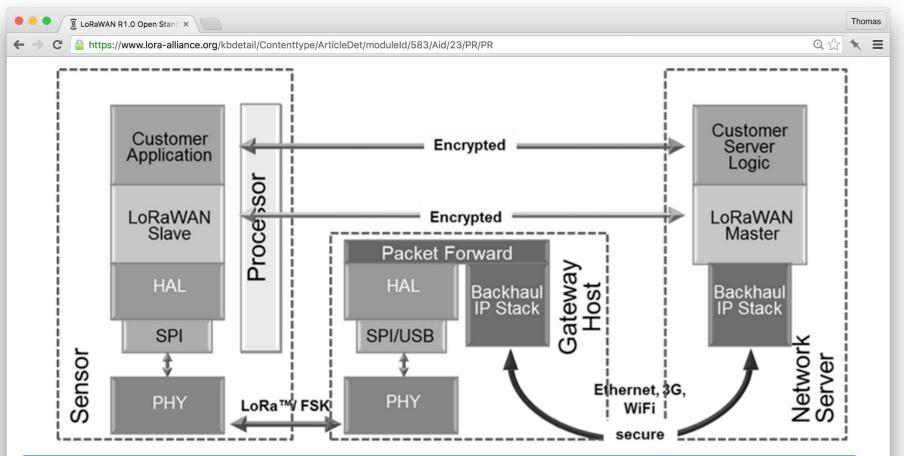
Gateways are **half-duplex**, if they are sending, they are not listening.

Duty cycle limitations of 1% apply per device.

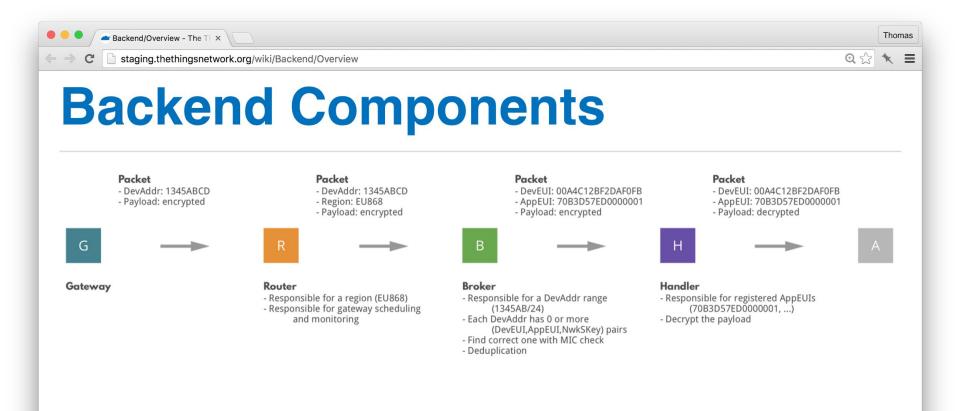
A **gateway** is also subject to the same limitation, but it has to **share its airtime** between all nodes around it.

Which use-cases could still work given this restriction?

Appendix B - Architecture

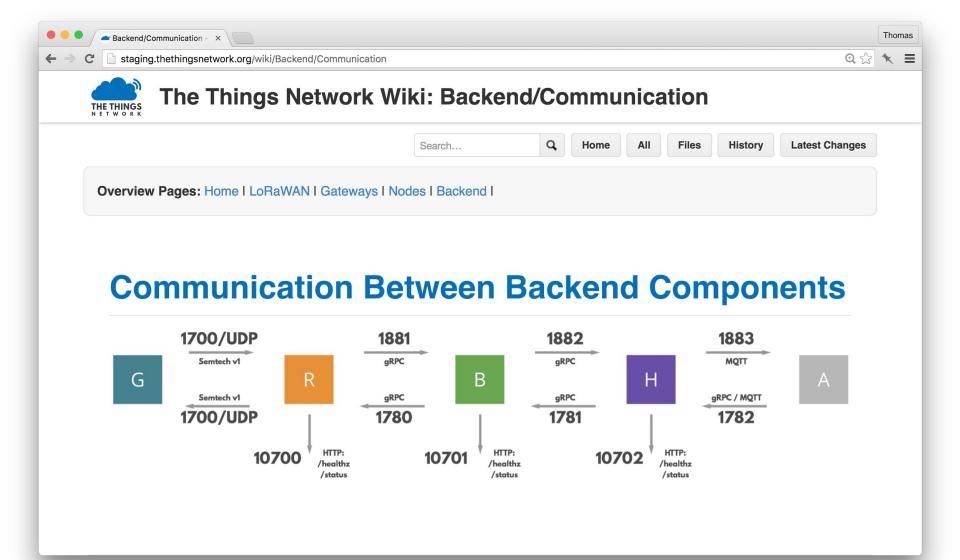


LoRaWAN network architecture is a typical star-of-stars topology in which the **gateways** are a transparent bridge relaying messages between **end-devices** and a central **network server**. Gateways are connected to the network server via standard IP connections, while end-devices use single-hop wireless communication to one or many

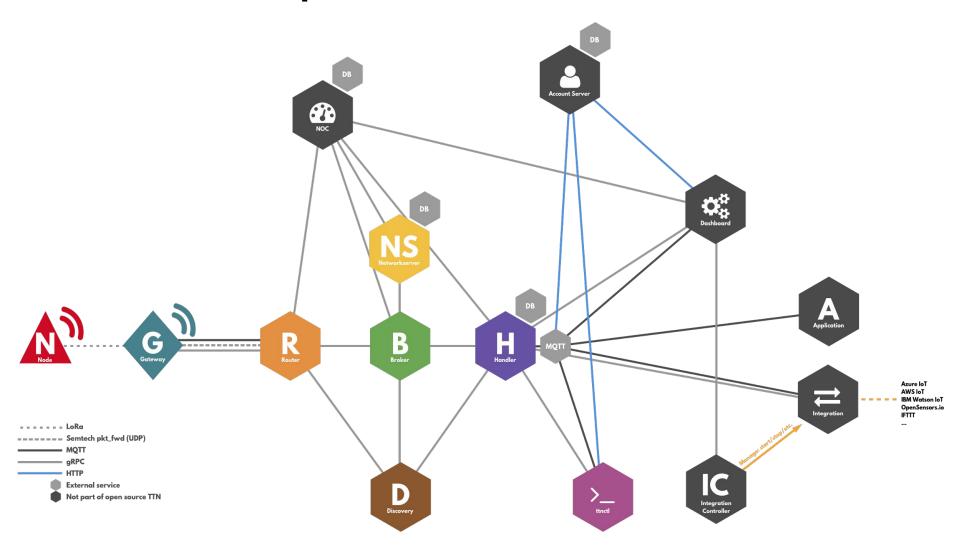


Backend Connect a Gateway I Connect an Application

Backend Components: Router | Broker | Handler



Backend components in detail



Appendix C - Community

The Things Network

OUR VISION

The Internet was created by people that connected their networks to allow traffic from, to and over their servers and cables to pass for free. As a result, there was abundant data communication and exponential innovation.

The Things Network is doing the same for the Internet of Things by creating abundant data connectivity. So applications and businesses can flourish.



New data connectivity technologies

New data network technologies allow for things to connect to the internet without using 3G or WiFi.

This technology is called LoRaWAN and it is perfect for the Internet of Things as it is low battery, long range, and low bandwidth. Imagine a network that can be used without cumbersome WiFi passwords. mobile subscriptions. and zero setup costs.



Low costs

Because the reach is very high and the cost of the equipment is low, covering an entire city can be done with a small investment. The city of Amsterdam was covered with only 10 gateways at the cost of 1200 dollars each.



Crowd sourced

Because the costs are very low, we do not have to rely on large telco corporations to build such a network.

Instead, we can crowdsource the network and make it public without any form of subscription. Our mission is to enable a network by the users for the users.

The Things Network

HOW TO CONTRIBUTE

Take a look at the most booming communities! We are highlighting the communities that are putting in work everyday. Want to find out why these communities are moving so fast? Take a look at their community pages.



Get coverage in your area by placing a Gateway

Place Gateway



Contribute to our open source code.

See our code



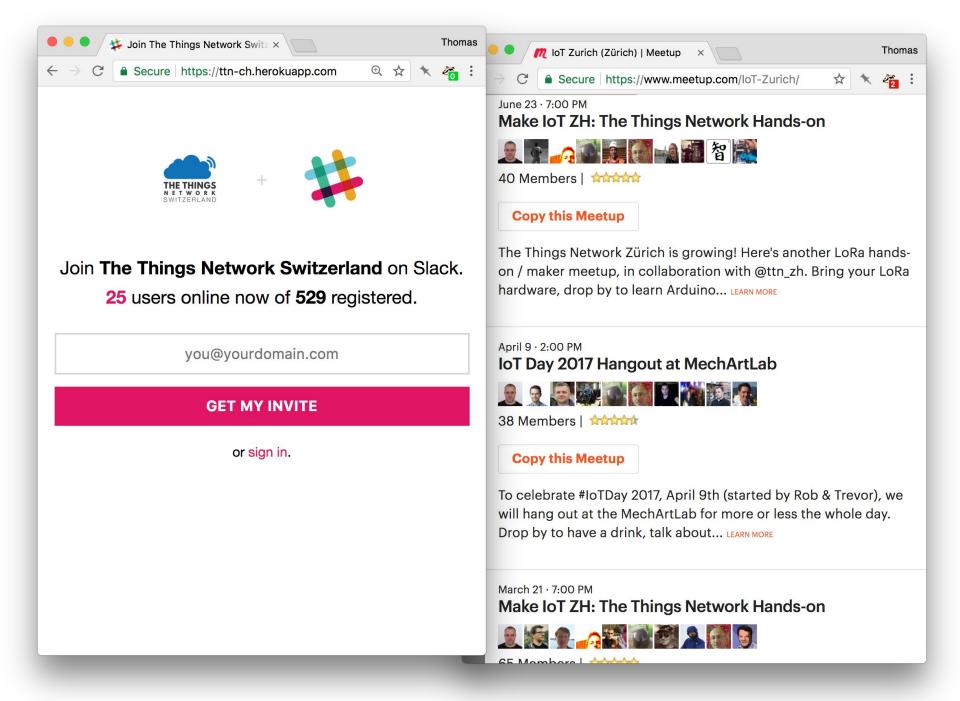
Help building our network through a community.

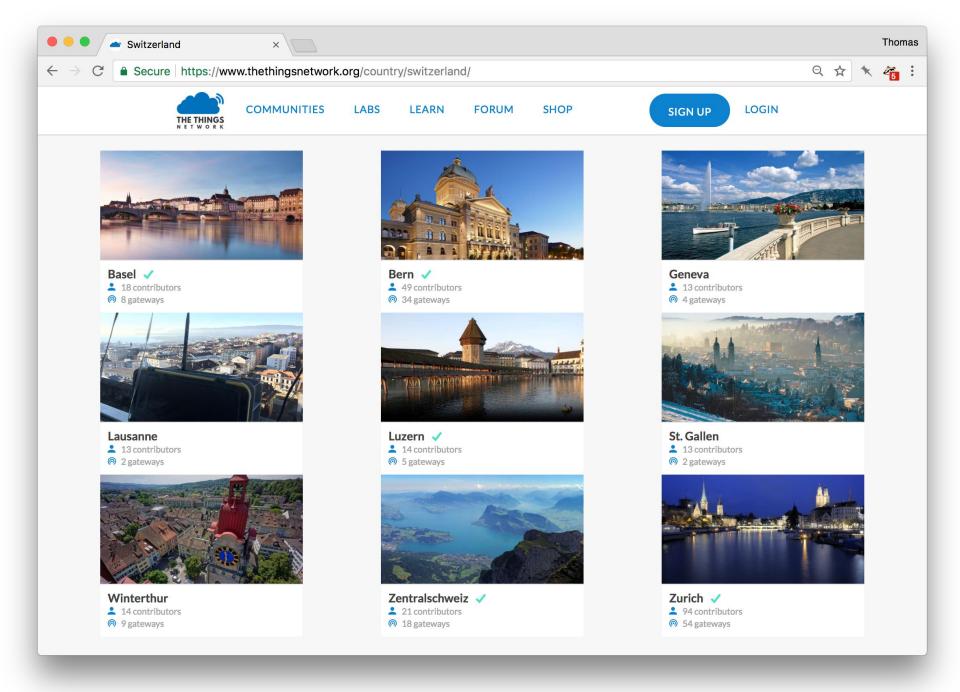
Communities

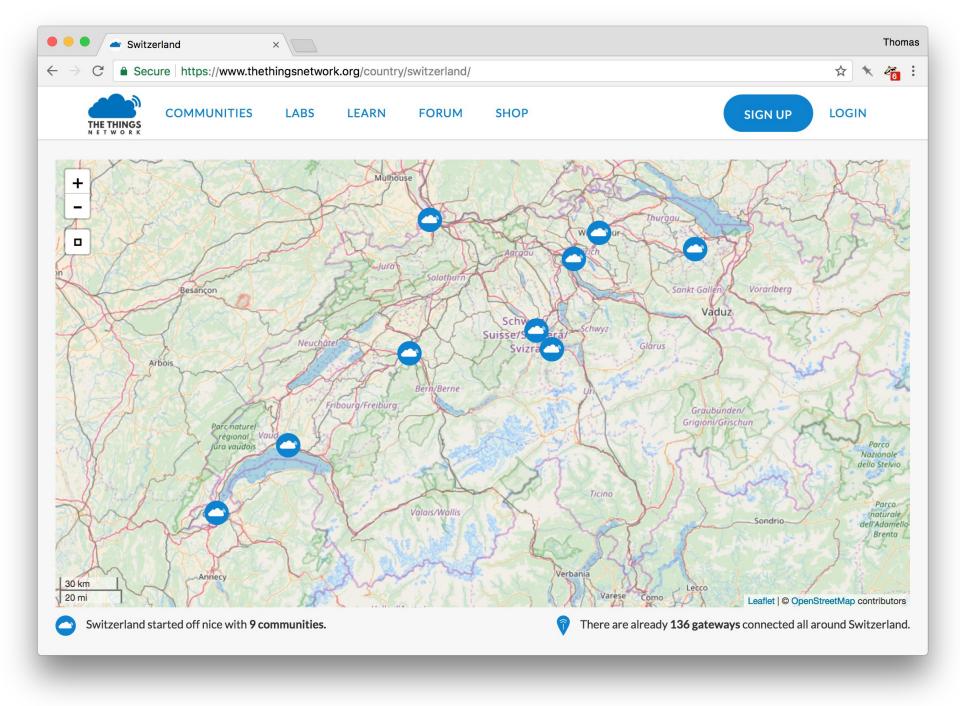


Work on use cases & connect with like-minded people on Labs.

Labs









We are a non-profit association working towards a future with networking infrastructure that is more open and accessible to everyone. Our work focuses on the operation of open networks, such as The Things Network, and on the promotion of knowledge of the technologies involved via public events such as MakeZurich.

Thanks

Questions?

Contact @gnz, @ttn_zs or @tamberg

And join https://thethingsnetwork.org/c/zentralschweiz/

Reducing E-waste

Tired of hacking?

Donate your hardware...

e.g. MechArtLab

Hohlstrasse 52

8004 Zürich